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В роботі наведені результати досліджень з визначення натягу в робочій зоні технологічного обладнання. Під робочою зоною мається на увазі зона в'язання, формування тканини, зона з'єднання матеріалів на швейній машині та інші. Використання рекурсивного підходу дозволяє послідовно визначати натяг ниток після кожного елемента системи подачі нитки по глибині її заправки з урахуванням умов взаємодії. Вихідний натяг нитки після взаємодії з напрямним елементом чи натягувачем для наступного елемента системи подачі нитки буде вхідним. Виконуючи послідовний перехід, можна визначати натяг в робочій зоні з урахуванням умов взаємодії нитки по всіх зонах технологічного обладнання.

Ключові слова: нитка, система подачі нитки, напрямні елементи, натягувачі нитки.

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USE OF RECURSIVE APPROACH FOR DETERMINATION OF PULL OF FILAMENTS IN WORKING ZONE OF TECHNOLOGICAL EQUIPMENT

The improvement of technological equipment must be based on realization of complex theoretical and experimental researches of terms of work of separate knots in the process of implementation of technological process. The system of serve of filaments plays a very important value in this process. It is related to that over imperfection of construction of the system of serve of filament brings to the height of her pull and origin of precipices. The decision of question of improvement of the system of serve of filaments on the technological machines of textile and sewing industry needs to be carried out in two directions: improvement of form of line of priming of filament, analysis of terms of co-operation of filament with structural elements that is included in the system of serve of filament (guiders of filament, devices for the pull of filament) and, on the base of it, optimization of maximum terms on an entrance and exit from these elements of such parameters as corners of scope of directing surfaces, radiuses of curvature of these surfaces. During realization of these researches after the first direction it is necessary line of priming of filament in the system of serve to break up on characteristic areas that plug in itself corresponding structural elements. For most technological machines of textile and sewing industry these areas will have similar character and will differ only by an amount and types of structural elements. Thus, a theme of the article is actual, that matters for the increase of the productivity technological equipment and quality of products that is produced. Objects and methods of research. The systems of serve of filaments on the technological machines of textile and sewing industry provide a necessary pull in a working zone. They include for itself separate knots for moving and accumulation of filament, structural elements that provide the construction of line of priming of filament on a technological equipment and grant of filament of corresponding pull. The technological processes of textile and sewing industry come forward as objects of research, where processing of filaments comes true. Theoretical and experimental researches, that are based on the use of textile materials, mechanics of filament, theory of resiliency, mathematical design, methods of theory of algorithms, analytical geometry, planning of experiment and statistical treatment of results of researches, come forward as basic methods of research. For software development modern languages were used objective - the oriented programming. Practical significance. Improvement of the system of serve of filaments on technological machines of textile and sewing industry allows to minimize their pull in a working zone, to decrease precipices, that has an important value for the improvement of technological processes from position of increase of the productivity of technological equipment and quality of products that is produced.

Keywords: filament, system of serve filaments, directing elements, devices for the pull of filament.

[1–4, 5, 9].

[1, 3, 6–11].

[1, 3, 5, 6, 7–11].

[1, 3, 9, 11].

[1–3, 5–10].

[2, 3–6].

[1-3, 8-11].

[1-3, 5-8].

$= n1-1.$

$j=1...n1.$

i
 v_j

$$P_1 = f_1(z_0, P_0),$$

$$P_2 = f_2(z_0, z_1, P_0, P_1),$$

.....

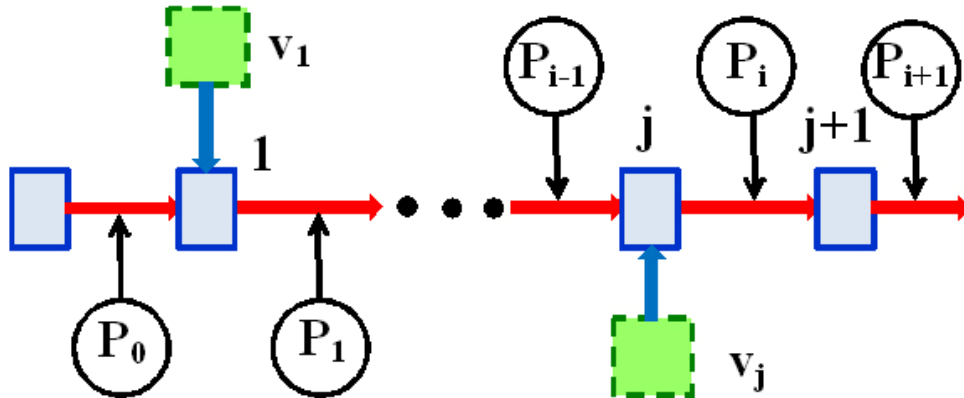
$$P_{i-1} = f_{i-1}(z_0, z_1, \dots, z_{i-1}, P_0, P_1, \dots, P_{i-1}),$$

$$P_i = f_i(z_0, z_1, \dots, z_{i-1}, z_i, P_0, P_1, \dots, P_{i-1}, P_i),$$

$$P_{i+1} = f_{i+1}(z_0, z_1, \dots, z_{i-1}, z_i, z_{i+1}, P_0, P_1, \dots, P_{i-1}, P_i, P_{i+1}),$$

(1)

$z_0, z_1, \dots, z_{i-1}, z_i, z_{i+1}$



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(. 2)

(. 2).

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3,

2

4, 5

6.

$v_1.$

(. 2)

3.

1,

v_1

2

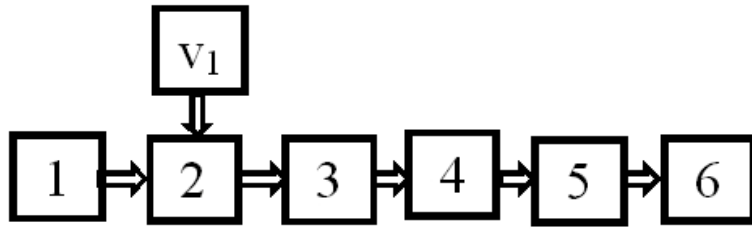
2,

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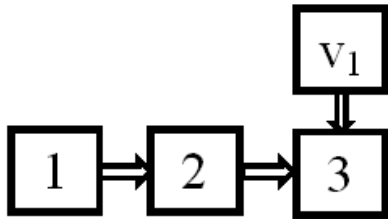
4

5

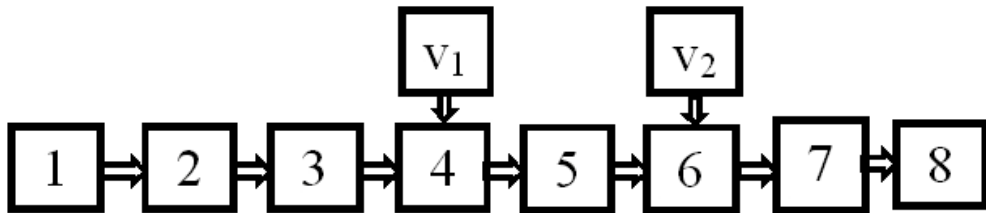
7 6 8 v_1 v_2



a



б



B

.2. , , [1, 3, 5, 6, 10] .2

$$P_{i+1} = P_i \left[1 + \frac{(R_j + r)}{[R_j + r(1 - \delta_{0j})]} \left(e^{\frac{\beta_j - a}{\sin \beta_j} R_j^{\beta_j} \phi_j} - 1 \right) \right] + \left[\frac{B}{2[R_j + r(1 - \delta_{0j})]^2} \right] - \left[\frac{B}{2[R_j + r(1 - \delta_{0j})]^2} \right] \times \left[1 + \frac{(R_j + r)}{[R_j + r(1 - \delta_{0j})]} \left(e^{\frac{\beta_j - a}{\sin \beta_j} R_{ms(j)}^{\beta_j} \phi_j} - 1 \right) \right], \quad (2)$$

$$\begin{matrix} P_{i+1} - & j & ; P_i - & j \\ ; R_j - & j & ; o_j - & j \\ & j & ; j - & j \\ & ; j - & & j \end{matrix} \quad (1) \quad (2)$$

[1-3].

$$P_{i+1} = b_0 + b_1 x_{i1} + b_2 x_{i2} + b_3 x_{i3} + b_{12} x_{i1} x_{i2} + b_{13} x_{i1} x_{i3} + b_{23} x_{i2} x_{i3} + b_{11} x_{i1}^2 + b_{22} x_{i2}^2 + b_{33} x_{i3}^2 \quad (3)$$

$$\begin{matrix} 1 - & 2 - \\ ; 3 - & ; b_0, b_1, b_2, b_3, b_{12}, b_{23}, b_{11}, b_{22}, b_{33} - \end{matrix}$$

(3).

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$$P_1 = 0.02 + 0.91P_0 + 0.01R_1 + 0.01P_0\phi_1, \tag{4}$$

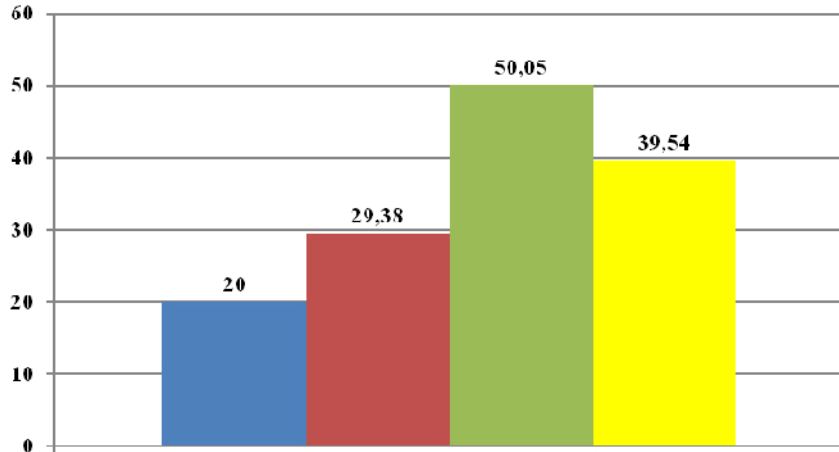
$$P_2 = 1.28 + 0.99P_1 - 0.32R_2 - 0.001\phi_2 + 0.003P_1\phi_2 + 0.001R_2\phi_2 + 0.02R_2^2, \tag{5}$$

$$P_3 = 2.86 + 1.08P_2 - 4.21R_3 + 0.004\phi_3 + 0.002P_2\phi_3 - 0.05P_2R_3 + 2.02R_3^2 \tag{6}$$

(4)-(5)

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